

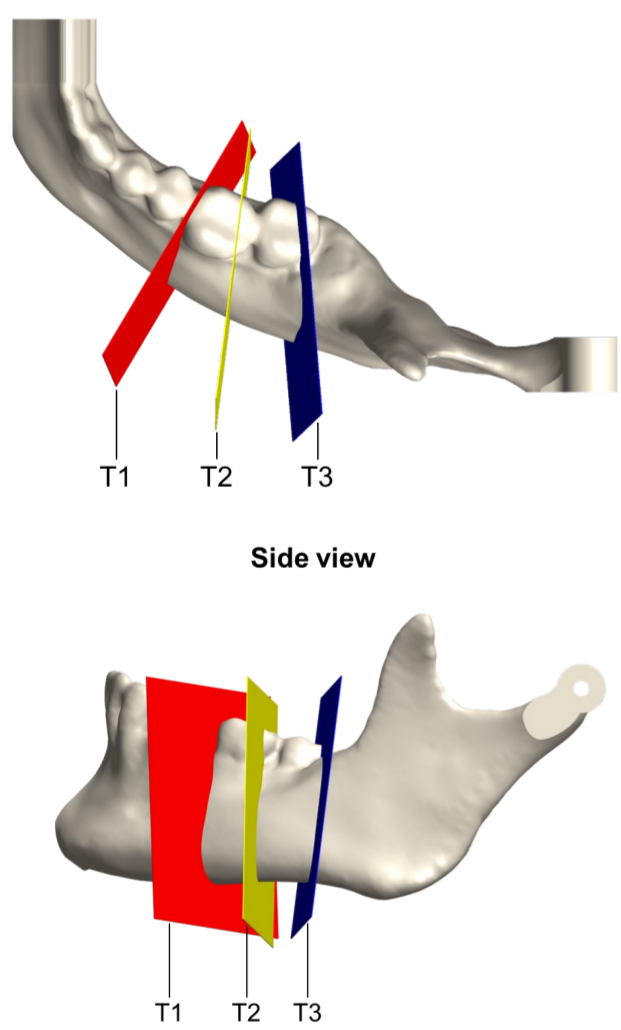
Concurrent Pre-Operative Surgical/Engineering Planning

- 1) **Cranio MaxilloFacial (CMF) surgery** has a broad scope with dual **goal: function + aesthetics** which demands high precision
- 2) **Preoperative planning** enables patient-specific guides/ implants design, cutting planes definition, osteosynthesis material selection, and surgical simulation
- 3) **Planning is a collaborative process:**
 - **surgeons** define osteotomies, resection margins, and clinical needs
 - **technicians** convert them into CAD models and 3D-printed guides tailored to the patient
- 4) **Iterative workflow** with continuous information exchange and shared decisions
- 5) **Outcomes and safety** hinge on the synergy between clinical and engineering expertise and on planning accuracy

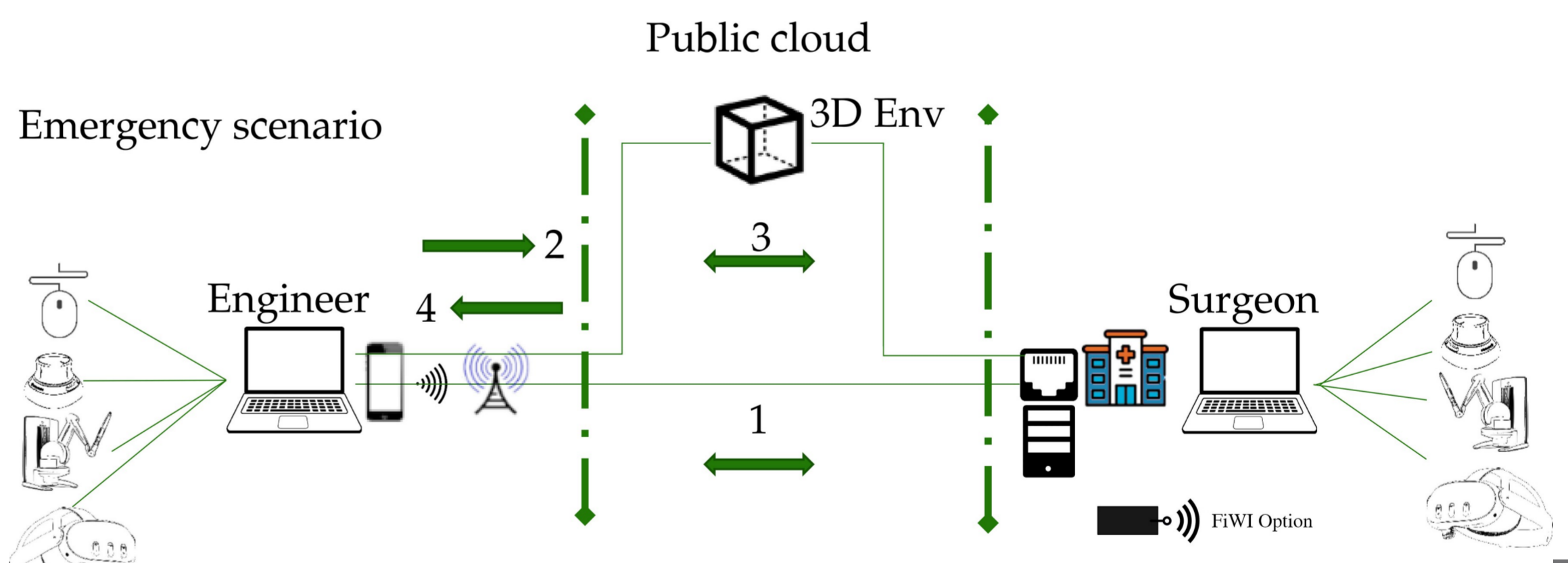
Current Gaps:

- **No structured, purpose-built platforms:** work happens via screen-sharing (e.g., Meet/Zoom) and voice
- **Ambiguous communication:** “a bit higher / more to the right” verbal cues without geometry-bound references or shared rulers/landmarks
- **No true co-editing in 3D:** participants can't jointly manipulate the same model, planes, or guides with guaranteed sync/versioning
- **Poor traceability:** limited annotation history, approvals, or audit trails linking decisions to anatomy and timestamps
- **Inefficient iterations:** slow back-and-forth, risk of misinterpretation, rework, and extended lead times for patient-specific guides
- **Governance & compliance gaps:** unclear roles/permissions, data security concerns, and inconsistent documentation

Resection planes



System architecture



- 1) **Shared 3D workspace:** real-time co-editing of anatomy, cutting planes, and guides with presence, locks, and role-based permissions
- 2) **Geometry-anchored communication:** pinned annotations on landmarks, rulers/angles/distances, templated comments (no more “a bit higher/right”)
- 3) **VR visualization** for immersive review
- 4) **Haptics:** haptic tools for tactile assessment of fit and access paths

Expected Outcome: fewer miscommunications, faster iterations, higher planning accuracy, and fully traceable decisions

